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Unravelling the effect of data augmentation transformations in polyp segmentation

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CARS

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* Deep learning for medical imaging analysis



Challenges [1-3]

- Relevance (clinical vs tech. interest)
 - Acceptance (black box)
 - Privacy and legal issues
- Lack of large annotated datasets
 - Class imbalance
 - Effective negative set
 - Weak annotations

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3. Tajbakhsh, N.; Jeyaseelan, L.; Li, Q.; Chiang, J.N.; Wu, Z.; Ding, X. Embracing Imperfect Datasets: A Review of Deep Learning Solutions for Medical Image Segmentation. *Med. Image Anal.* **2020**, 63, 101693.

Introduction

- * Data augmentation [1-4]
 - * Manipulate image appearance, quality, or layout
 - * Reduce overfitting
 - * Preserve label/mask

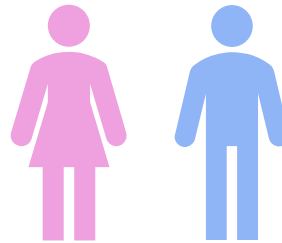


Which is the best data augmentation strategy for a particular problem?

1. Bloice, M.D.; Roth, P.M.; Holzinger, A.; Murphy, R. Biomedical image augmentation using Augmentor. *Bioinformatics* 2019, 35, 4522–4524
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* Colorectal cancer [1,2]

Type	Incidence	Mortality
Breast	2.088.849	626.679
Colorectum	826.303	396.568
Cervix uteri	725.352	576.060



Type	Incidence	Mortality
Lung	1.368.524	1.184.947
Prostate	1.276.106	358.989
Colorectum	1.026.215	484.224

* Computer-aided detection (CAdE) and diagnosis (CAdx) in colonoscopy [3]:

- * Adequacy of inspection technique
- * Polyp identification
- * Optical biopsy

1, Cancer Today. <https://bit.ly/2XjNgbo>

2, Cancer Today. <https://bit.ly/3gajQVM>

3. Byrne, M.F.; Shahidi, N.; Rex, D.K. Will Computer-Aided Detection and Diagnosis Revolutionize Colonoscopy? Gastroenterology 2017, 153, 1460-1464.e1.

Introduction

* Publicly available datasets for polyp segmentation:

	Database	# Images	Ground truth
Medical images	CVC-EndoSceneStill	912	Binary mask (border, polyp, lumen and specular lights)
	Kvasir-SEG	1000	Binary mask (polyp)
	CVC-VideoClinicDB	36 videos (>30,000 frames)	Binary mask with elliptical approximation
Natural images	ImageNet	>14,000,000	Label and bounding box
	MSCoco	330,000	Binary mask, bounding box, person keypoints, captions
	PascalVOC	>19,000 images (>40,000 instances)	Binary mask and bounding box

Introduction

Work	Year	Rotation	Width Shift	Height shift	Shear	Zoom	Flip	Contrast	Brightness
Jha [1]	2020	--	-	-	-	✓	✓	-	✓
Guo [2]	2019	✓	-	-	-	✓	✓	-	✓
Kang [3]	2019	(-45°, 45°)	-	-	(-16°, 16°)	(0.5, 1.5)	✓	(0.5, 1.5)	(0.8, 1.5)
Akbari [4]	2018	10° interval, between 0°-290°	-	-	-	-	✓	-	-
Brandao [5]	2018	-	-	-	-	-	✓	-	-
Wichakam [6]	2018	up to 180°	(0, 20%)	(0, 20%)	up to 20%	(-0.8, 1.2)	✓	-	-
Wickstrom [7]	2018	(-90°, 90°)	-	-	(0, 0.4)	(0.8, 1.2)	-	-	-
Bardhi [8]	2017	✓	✓	✓	✓	-	✓	-	-
Li [9]	2017	✓	✓	✓	-	-	-	✓	-
Vázquez [10]	2017	(0°, 180°)	-	-	(0, 0.4)	(0.9, 1.1)	-	-	-

References are provided at the end of the presentation

Objective



- * **HYPOTHESIS:**

The application of different transformations as well as different ranges for the same transformation might lead to differences in performance

- * **OBJECTIVE:**

To elucidate the effect of different image transformations and their ranges used for data augmentation for polyp segmentation

Material and Methods

ORIGINAL IMAGE

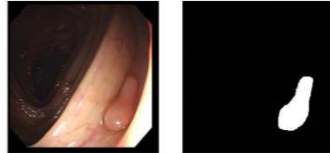
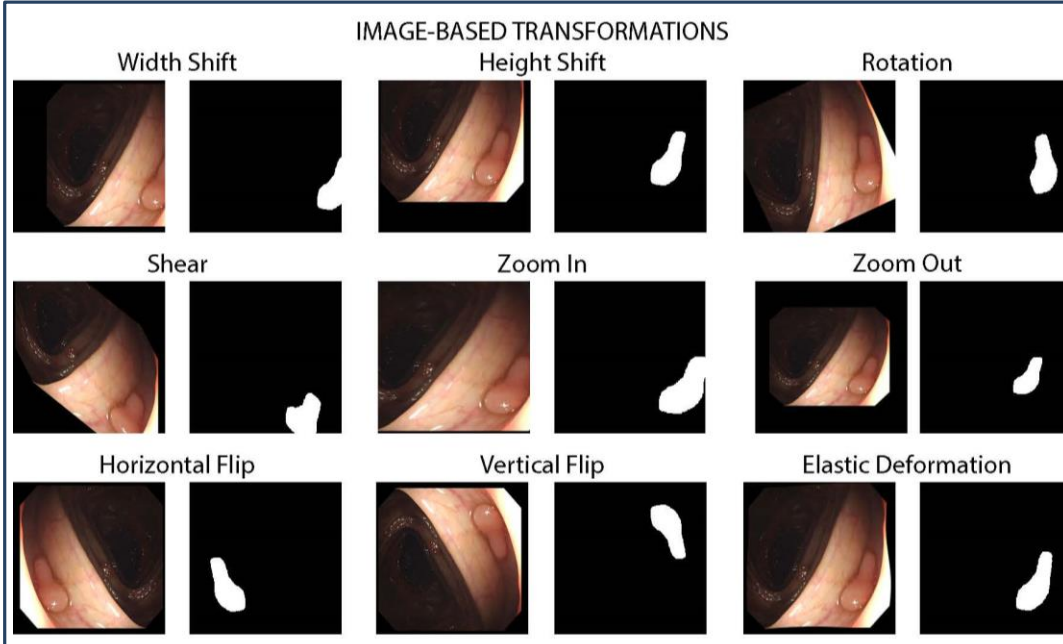
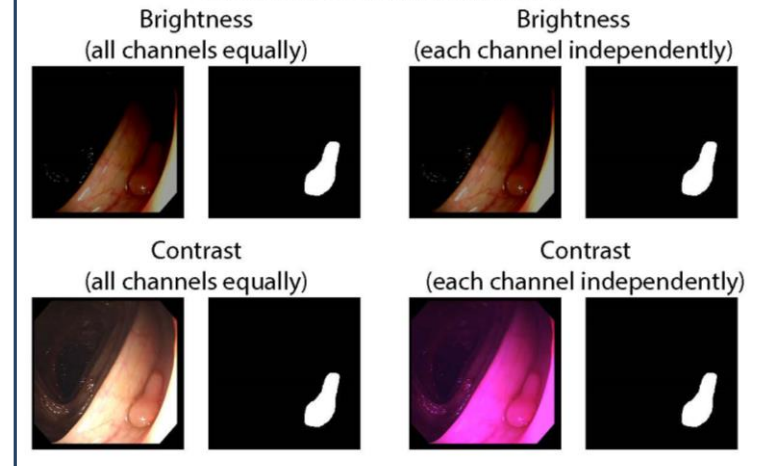


IMAGE-BASED TRANSFORMATIONS



PIXEL-BASED TRANSFORMATIONS



PROBLEM-BASED TRANSFORMATIONS

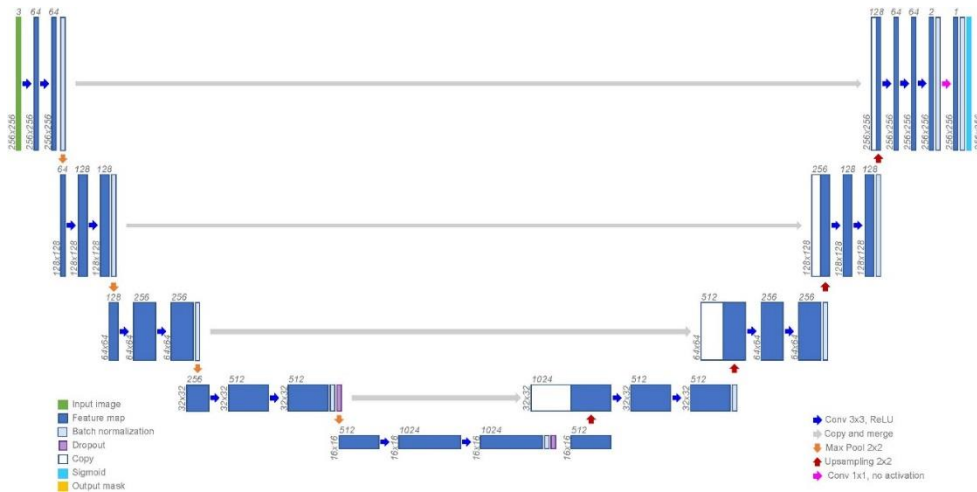


Material and Methods

- * Architecture: U-Net based
 - * pre-trained using CVC-VideoClinicDB

* Loss: $Loss = -\frac{1}{n} \sum_{i,j} (y_{i,j} \log \hat{y}_{i,j} + (1 - \hat{y}_{i,j}) \log(1 - \hat{y}_{i,j})) - \log J$

* Metric: $J = IoU(A, B) = \frac{|A \cap B|}{|A \cup B|} = \frac{|A \cap B|}{|A| + |B| - |A \cap B|}$



- * Fixed training parameters
- * Baseline: no data augmentation
- * Each experiment is repeated 10 times
- * 15 epochs
- * Data augmentation on the flow
- * Dataset: CVC-EndoSceneStill
 - * Training set: 547
 - * Validation set: 183
 - * Test set: 182
- * Statistical analysis
 - * Kolmogorov-Smirnov
 - * Wilcoxon-signed rank test

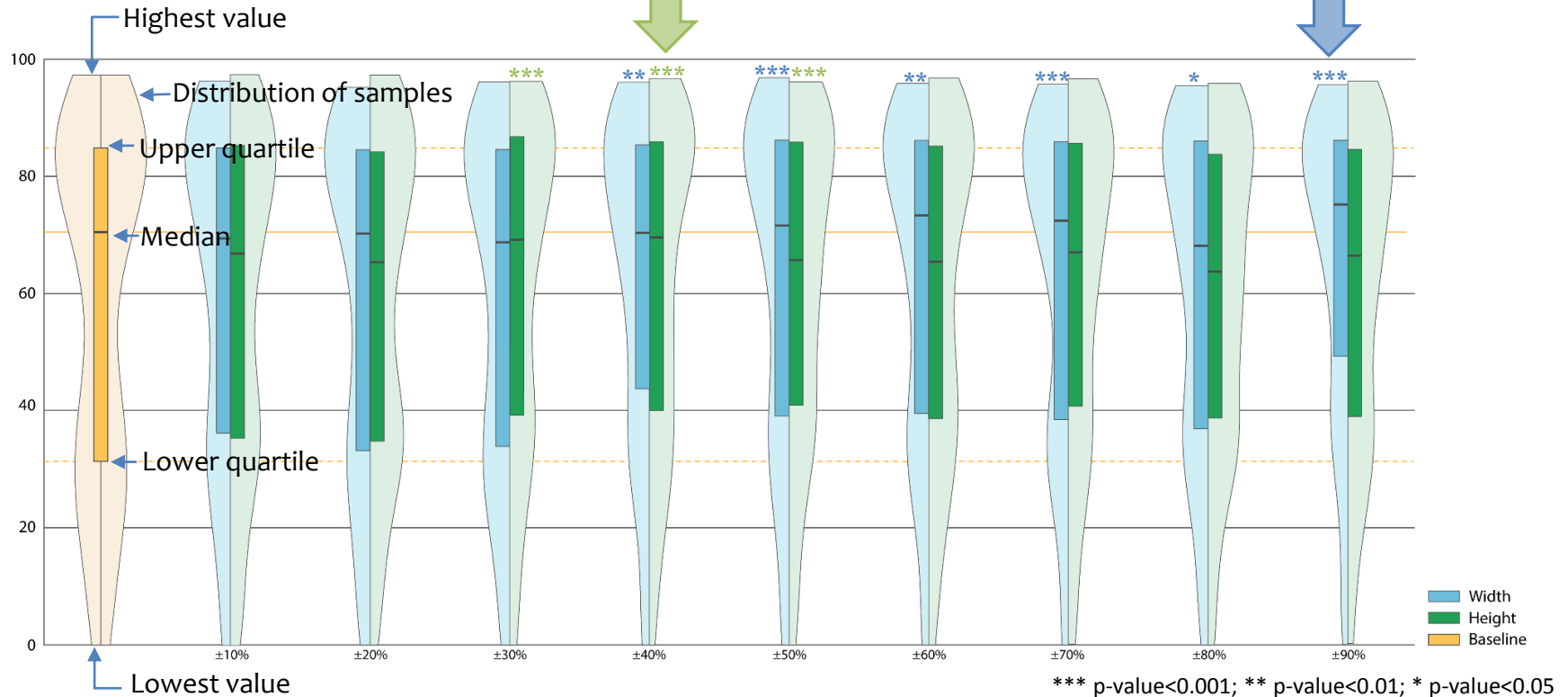
Results



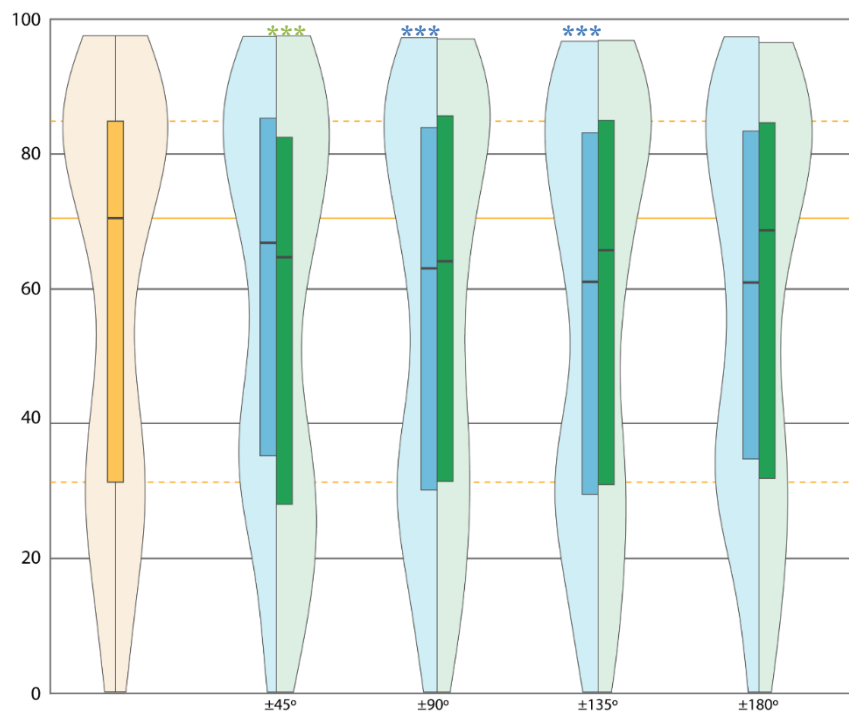
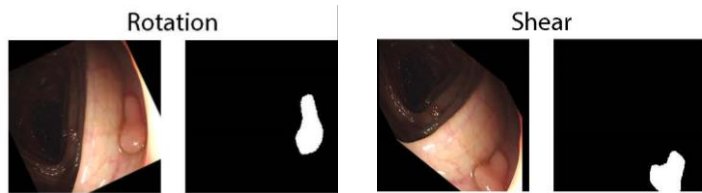
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Width Shift

Height Shift

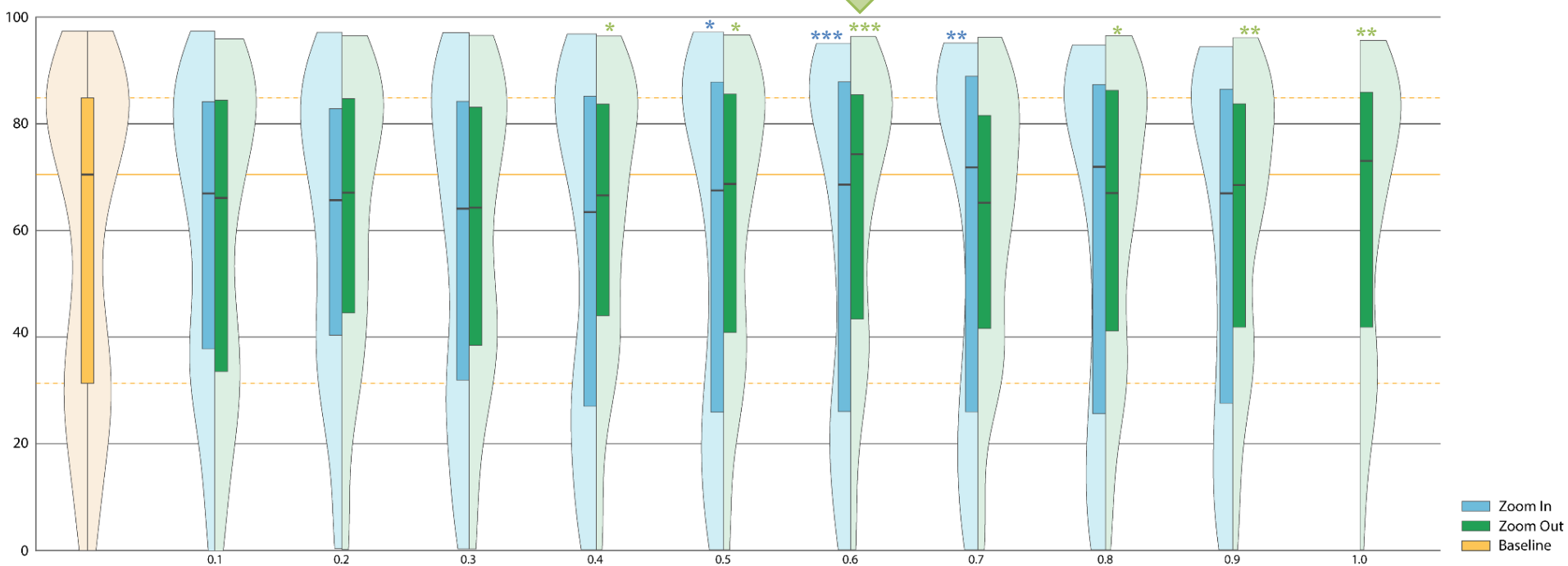


Results



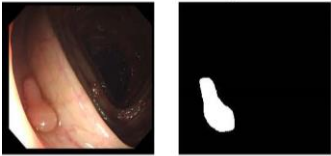
*** p-value<0.001; ** p-value<0.01; * p-value<0.05

Results

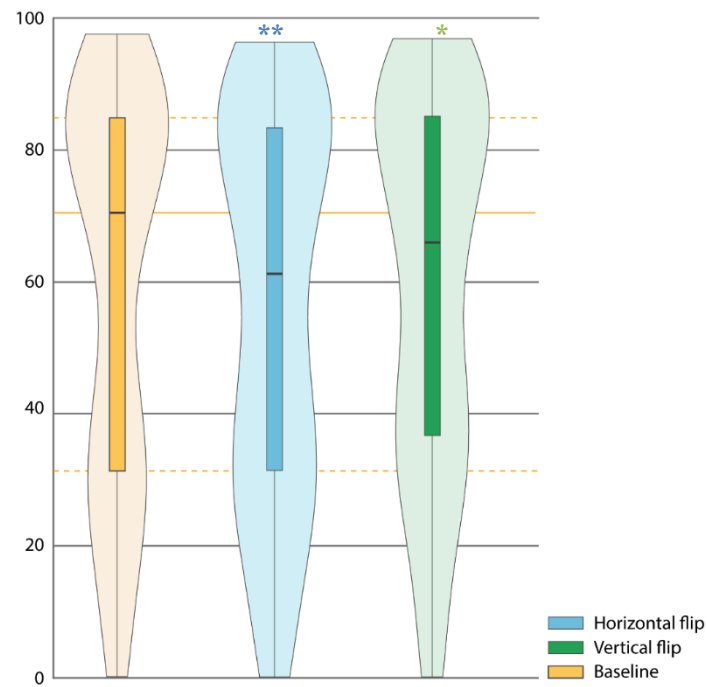
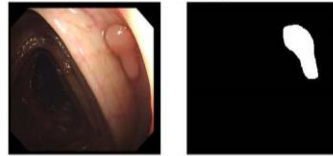


Results

Horizontal Flip



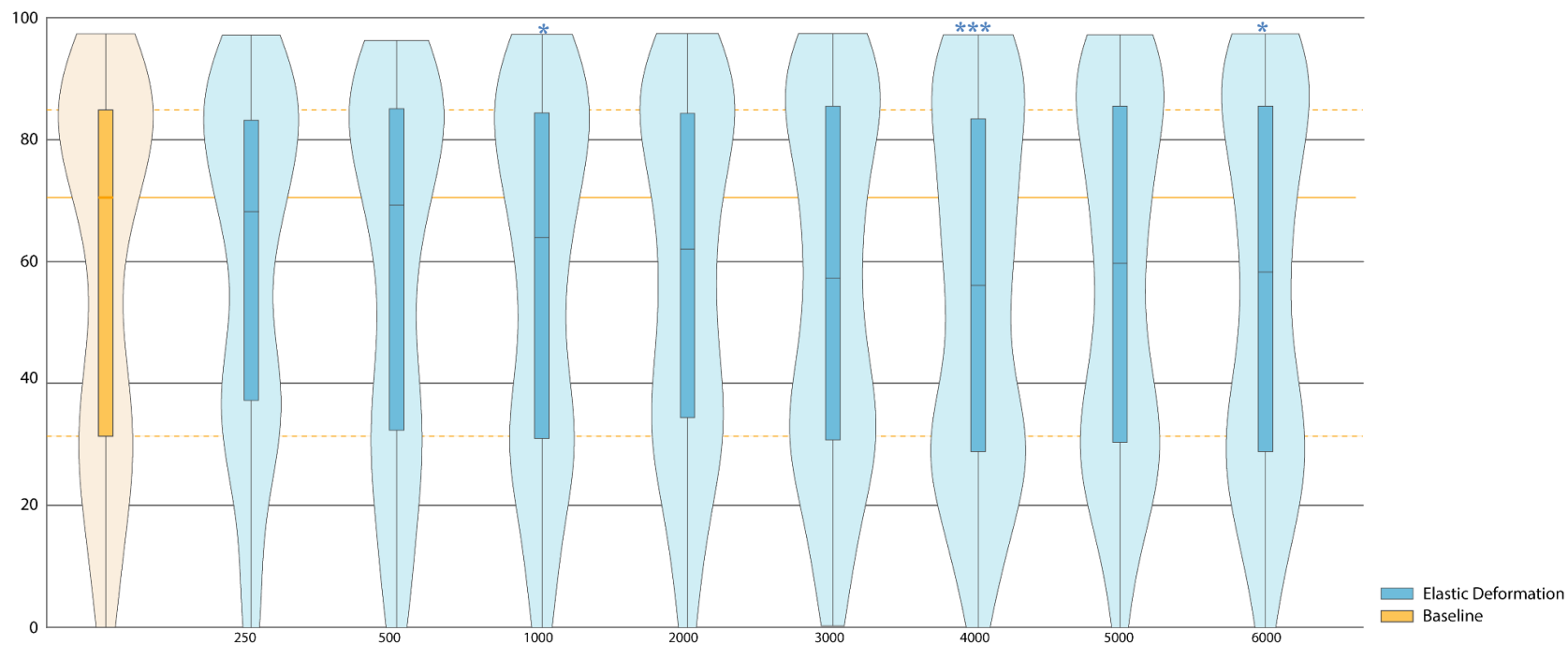
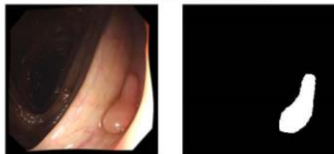
Vertical Flip



*** p-value<0.001; ** p-value<0.01; * p-value<0.05

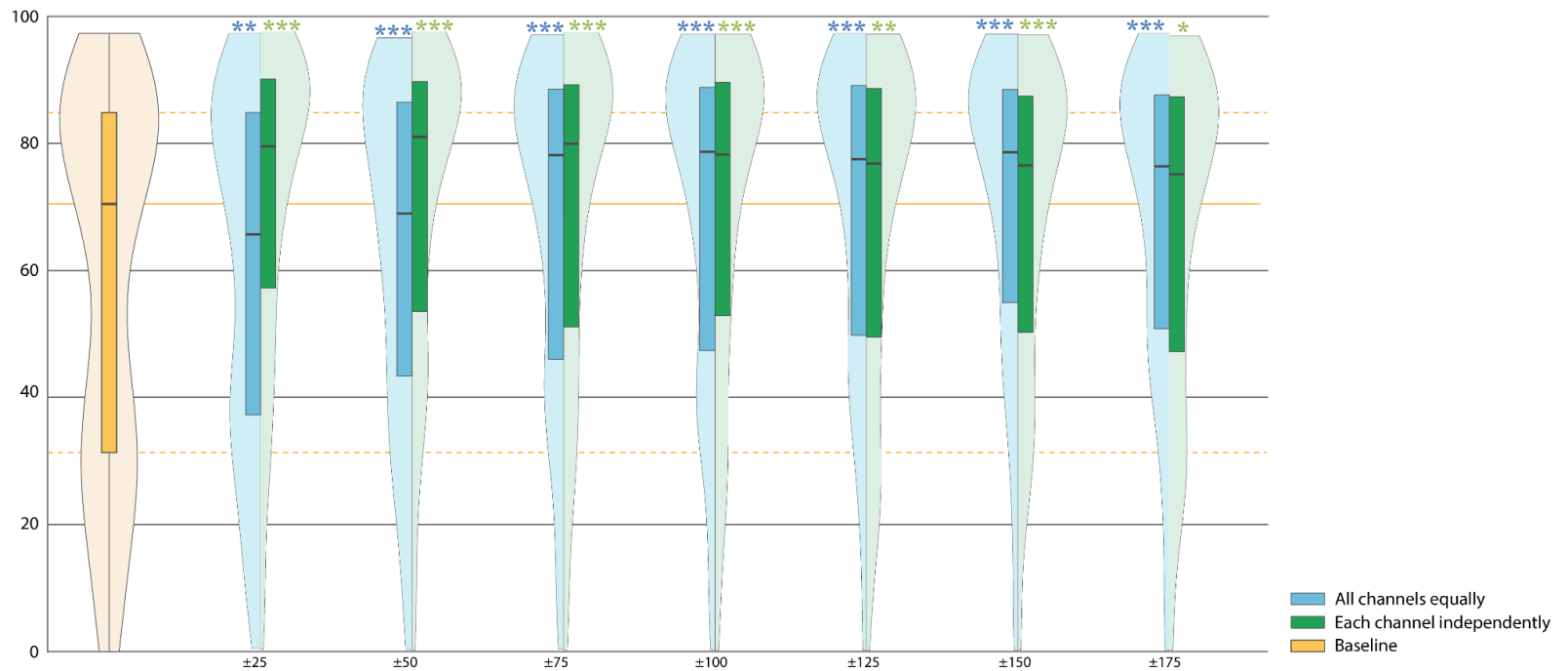
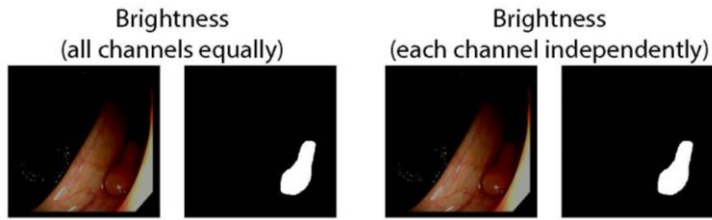
Results

Elastic Deformation

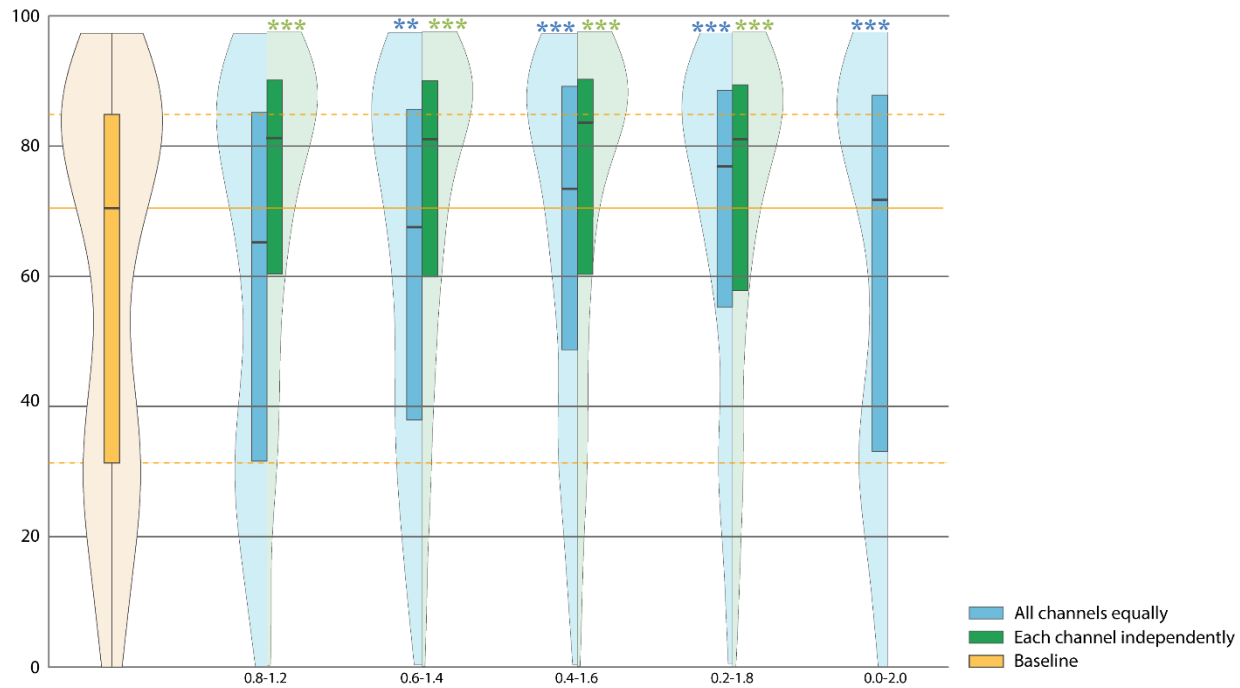
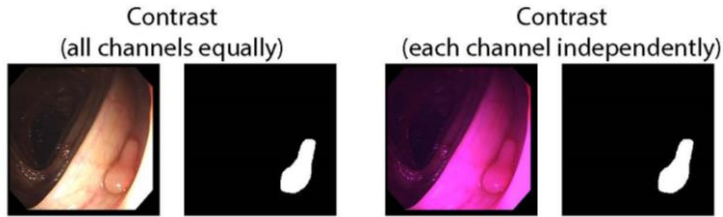


*** p-value<0.001; ** p-value<0.01; * p-value<0.05

Results



Results



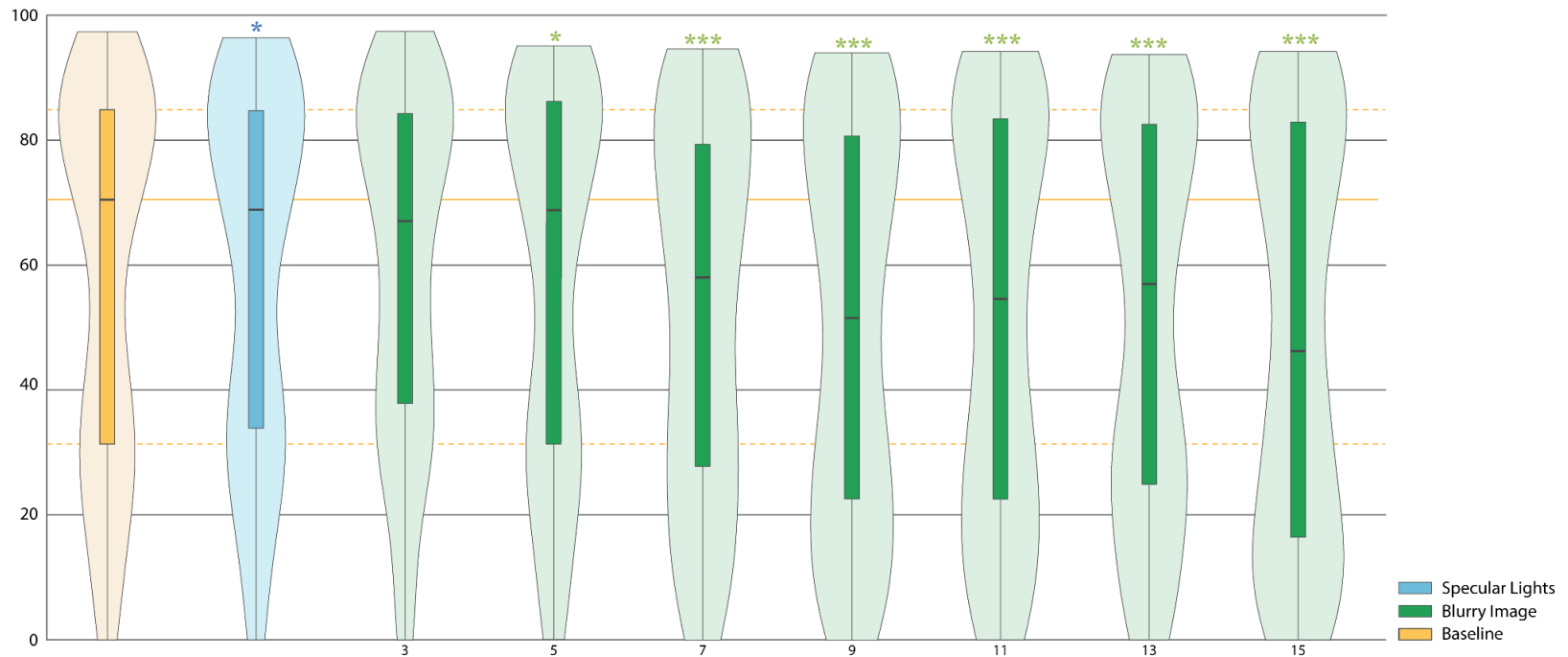
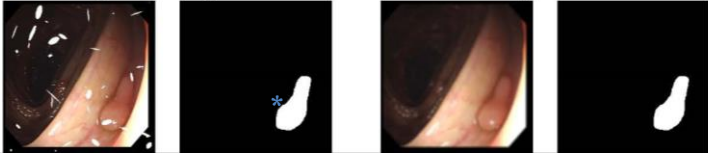
*** p-value<0.001; ** p-value<0.01; * p-value<0.05

Results

PROBLEM-BASED TRANSFORMATIONS

Specular Lights

Blurry Frames



*** p-value<0.001; ** p-value<0.01; * p-value<0.05

Results



- * Best improvements:
 - * Width: $\pm 40\%$
 - * Height: $\pm 90\%$
 - * Zoom in: 0.6
 - * Brightness: ± 25 , each channel independently
 - * Contrast: 0.4-1.6, each channel independently
 - * Inclusion of specular lights

Conclusions

- * Three groups of transformations can be established:
 - * Transformations that always improve the performance:
 - * vertical flip
 - * changes on brightness
 - * changes on contrast
 - * inclusion of specular lights
 - * Transformations that always hinder the performance:
 - * rotation
 - * shear
 - * horizontal flip
 - * elastic deformation
 - * blurry frames (mean filter)
 - * Transformations whose effect on performance depends on the selected range:
 - * height shift
 - * width shift
 - * zoom in
 - * zoom out

Conclusions



- * Different transformations and ranges lead to differences in model performance.
- * Pixel-based transformations show a great potential to improve polyp segmentation.
- * Image-based transformations and their ranges should be carefully selected to not hinder the model performance and obtain the expected benefits of data augmentation.

Future works



- * Study different combinations of transformations
- * Analyse the effect of these transformations in a different dataset (Kvasir-SEG)

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Thank you for your attention

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